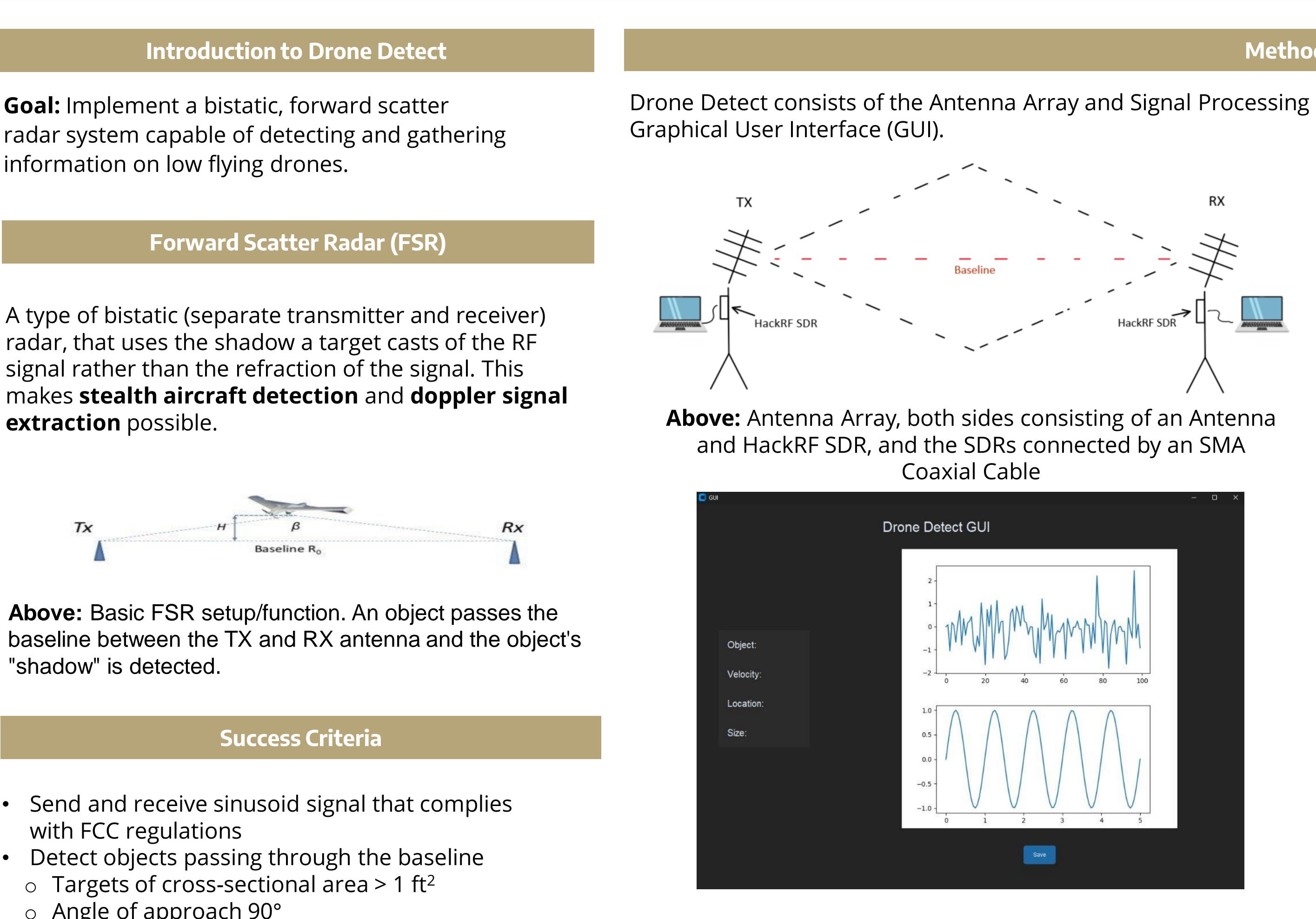


# **DRONE DETECT**

# STUDENTS: David Phan, McCoy Spink, Spencer Madrid, Sean Budomo, Shuting Shao, Shoh Schulz, Gokul Gopakumar

**Goal:** Implement a bistatic, forward scatter radar system capable of detecting and gathering information on low flying drones.

A type of bistatic (separate transmitter and receiver) radar, that uses the shadow a target casts of the RF signal rather than the refraction of the signal. This extraction possible.



"shadow" is detected.

- Send and receive sinusoid signal that complies with FCC regulations
- Detect objects passing through the baseline  $\circ$  Targets of cross-sectional area > 1 ft<sup>2</sup>
- Angle of approach 90°
- Extract Doppler information from moving target (velocity)
- Create a GUI to show relevant frequency and system data in real time





**Above:** Signal Processing GUI on-screen display

**ADVISERS:** Mike VanDooren, Luke Firsching **SPONSOR: ANPC** 

# Methodology





### Future Work, References, and Acknowledgments

- Improve speed of real-time GU
- Optimize sensors to allow for m accurate readings
- Implement more complex signation processing to allow:
- Identifying target angle in relati to baseline
- Adjust resulting velocity calcula based on the angle



## **Above:** *(Left)* TX antenna, 916-CW-RCL-SMA Monopole Antenna with Ground Plane and (Right) RX antenna, RFSPACE TSA400 Antenna with Ground Plane.

Left: Antenna array during outdoor testing

JI more	Faculty: John Reece Teaching Assistant: Tim Amish Industry Mentor: Luke Firsching, Mike VanDooren
al	[1] "Radar: Introduction to Radar Systems - Online Course." Radar: Introduction to Radar Systems - Online Course   MIT
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